Task:03 Use Case Scenario of Autonomous Farming Vehicles which avoid Obstacles

**Main Aim:**

While Farming if a farming vehicle is moving around the designated path and encounters an obstacle e.g another vehicle

**Requirements**

How will it encounter it?

Will it stop?

How long will it stop?

What path will it take to start its journey again?

**Sensors:**

Usb Camera

Laser Range Finder